Ph.D. (in Electronics and Communication Engineering) Entrance Examination, 2022

Section 1: Engineering Mathematics:

Linear Algebra: Vector space, basis, linear dependence and independence, matrix algebra, eigenvalues and eigenvectors, rank, solution of linear equations- existence and uniqueness

Calculus: Mean value theorems, theorems of integral calculus, evaluation of definite and improper integrals, partial derivatives, maxima and minima, multiple integrals, line, surface and volume integrals, Taylor series.

Differential Equations: First order equations (linear and nonlinear), higher order linear differential equations, Cauchy's and Euler's equations, methods of solution using variation of parameters, complementary function and particular integral, partial differential equations, variable separable method, initial and boundary value problems.

Vector Analysis: Vectors in plane and space, vector operations, gradient, divergence and curl, Gauss's, Green's and Stokes' theorems.

Complex Analysis: Analytic functions, Cauchy's integral theorem, Cauchy's integral formula, sequences, series, convergence tests, Taylor and Laurent series, residue theorem

Probability and Statistics: Mean, median, mode, standard deviation, combinatorial probability, probability distributions, binomial distribution, Poisson distribution, exponential distribution, normal distribution, joint and conditional probability.

Section 2: Networks, Signals and Systems

Circuit analysis: Node and mesh analysis, superposition, Thevenin's theorem, Norton's theorem, reciprocity. Sinusoidal steady state analysis: phasors, complex power, maximum power transfer. Time and frequency domain analysis of linear circuits: RL, RC and RLC circuits, solution of network equations using Laplace transform. Linear 2-port network parameters, wye-delta transformation. Continuous-time signals: Fourier series and Fourier transform, sampling theorem and applications. Discrete-time signals: DTFT, DFT, z-transform, discrete-time processing of continuous-time signals. LTI systems: definition and properties, causality, stability, impulse response, convolution, poles and zeroes, frequency response, group delay, phase delay.

Section 3: Electronic Devices:

Energy bands in intrinsic and extrinsic semiconductors, equilibrium carrier concentration, direct and indirect band-gap semiconductors. Carrier transport: diffusion current, drift current, mobility and resistivity, generation and recombination of carriers, Poisson and continuity equations. P-N junction, Zener diode, BJT, MOS capacitor, MOSFET, LED, photo diode and solar cell.

Section 4: Analog Circuits:

Diode circuits: clipping, clamping and rectifiers, BJT and MOSFET amplifiers: biasing, ac coupling, small signal analysis, frequency response. Current mirrors and differential amplifiers. Op-amp circuits: Amplifiers, summers, differentiators, integrators, active filters, Schmitt triggers and oscillators.

Section 5: Digital Circuits and Microprocessor:

Number representations: binary, integer and floating-point- numbers. Combinatorial circuits: Boolean algebra, minimization of functions using Boolean identities and Karnaugh map, logic gates and their static CMOS implementations, arithmetic circuits, code converters, multiplexers, decodersSequential circuits: latches and flip-flops, counters, shift-registers, finite

state machines, propagation delay, setup and hold time, critical path delay.Data converters: sample and hold circuits, ADCs and DACs.Semiconductor memories: ROM, SRAM, DRAM. 8085 Microprocessor: Programmers model, register structure, addressing modes and assembly languages, Interrupts. Peripherals: Programmable interrupt controller (8259), programmable peripheral interface (8255), serial communication (8251), programmable timer and event counter (8254) and DMA controller (8257

Section 6: Control Systems:

Basic control system components; Feedback principle; Transfer function; Block diagram representation; Signal flow graph; Transient and steady-state analysis of LTI systems; Frequency response; Routh-Hurwitz and Nyquist stability criteria; Bode and root-locus plots; Lag, lead and laglead compensation; State variable model and solution of state equation of LTI systems.

Section 7: Communications and microwave:

Random processes: autocorrelation and power spectral density, properties of white noise, filtering of random signals through LTI systems. Analog communications: amplitude modulation and demodulation, angle modulation and demodulation, spectra of AM and FM, superheterodyne receivers. Information theory: entropy, mutual information and channel capacity theorem. Digital communications: PCM, DPCM, digital modulation schemes (ASK, PSK, FSK, QAM), bandwidth, inter-symbol interference, MAP, ML detection, matched filter receiver, SNR and BER. Fundamentals of error correction, Hamming codes, CRC.

Passive Microwave Devices and Components - Reciprocal and non-reciprocal devices and their applications. Guided and Free Space Propagation. Active Microwave Devices - Tubes and Solid State Devices, their principles and applications. Measurement Systems and Measurement Techniques. Microwave Materials and their Properties

Section 8: Electromagnetics:

Maxwell's equations: differential and integral forms and their interpretation, boundary conditions, wave equation, Poynting vector. Plane waves and properties: reflection and refraction, polarization, phase and group velocity, propagation through various media, skin depth. Transmission lines: equations, characteristic impedance, impedance matching, impedance transformation, S-parameters, Smith chart. Rectangular and circular waveguides, light propagation in optical fibers, dipole and monopole antennas, linear antenna arrays.

Section 9: Electrical Machines:

Single phase transformer: equivalent circuit, phasor diagram, open circuit and short circuit tests, regulation and efficiency; Three-phase transformers: connections, vector groups, parallel operation; Auto-transformer, Electromechanical energy conversion principles; DC machines: separately excited, series and shunt, motoring and generating mode of operation and their characteristics, speed control of dc motors; Three-phase induction machines: principle of operation, types, performance, torque-speed characteristics, no-load and blocked-rotor tests, equivalent circuit, starting and speed control; Operating principle of single-phase induction motors; Synchronous machines: cylindrical and salient pole machines, performance and characteristics, regulation and parallel operation of generators, starting of synchronous motors; Types of losses and efficiency calculations of electric machines

Section 10: Power Electronics

Static V-I characteristics and firing/gating circuits for Thyristor, MOSFET, IGBT; DC to DC conversion: Buck, Boost and Buck-Boost Converters; Single and three-phase configuration of uncontrolled rectifiers; Voltage and Current commutated Thyristor based converters; Bidirectional ac to dc voltage source converters; Magnitude and Phase of line current harmonics for uncontrolled and thyristor based converters; Power factor and Distortion Factor of ac to dc converters; Single-phase and three-phase voltage and current source inverters, sinusoidal pulse width modulation.

11. Sensors and Bioinstrumentation:

Sensors – resistive, capacitive, inductive, piezoelectric, Hall effect, electrochemical, optical; Sensor signal conditioning circuits; application of LASER in sensing and therapy. Origin of biopotentials and their measurement techniques– ECG, EEG, EMG, ERG, EOG, GSR, PCG, Principles of measuring blood pressure, body temperature, volume and flow in arteries, veins and tissues, respiratory measurements and cardiac output measurement. Operating principle of medical equipment -sphygmomanometer, ventilator, cardiac pacemaker, defibrillator, pulse oximeter, hemodialyzer; Electrical Isolation (optical and electrical) and Safety of Biomedical Instruments.